

## PID Configuration

**PID - Rung #2:0 - PD11:0**

Controller Gain, Kc: 1.2	Setpoint: 120
Reset Term, Ti: 2.70	Setpoint MAX(Smax): 200
Rate Term, Td: 0.00	Setpoint MIN(Smin): 0
Loop Update Time: 1.00	Process Variable PV: 0
Control Mode: E = SP - PV	Control Output CV (%): 60
PID Control: Manual	Output Max CV(%): 100
Time Mode: Timed	Output Min CV(%): 0
Limit Output CV: Yes	Scaled Error: 0
Deadband: 0	Feed Forward Bias: 0

